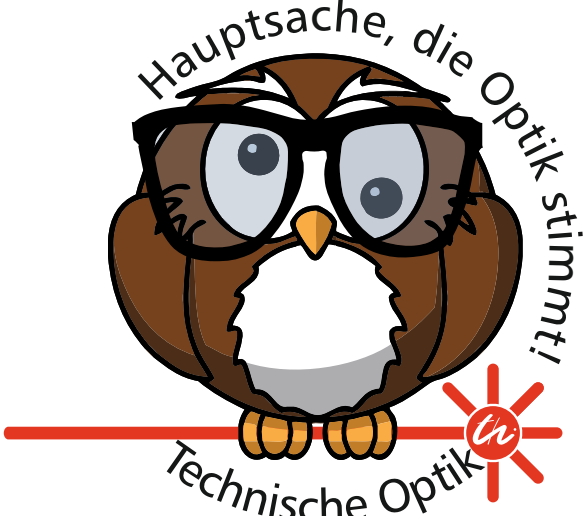


PARAX 2.0

A Software Tool with a Powerful GUI for Initial Step Optical Design

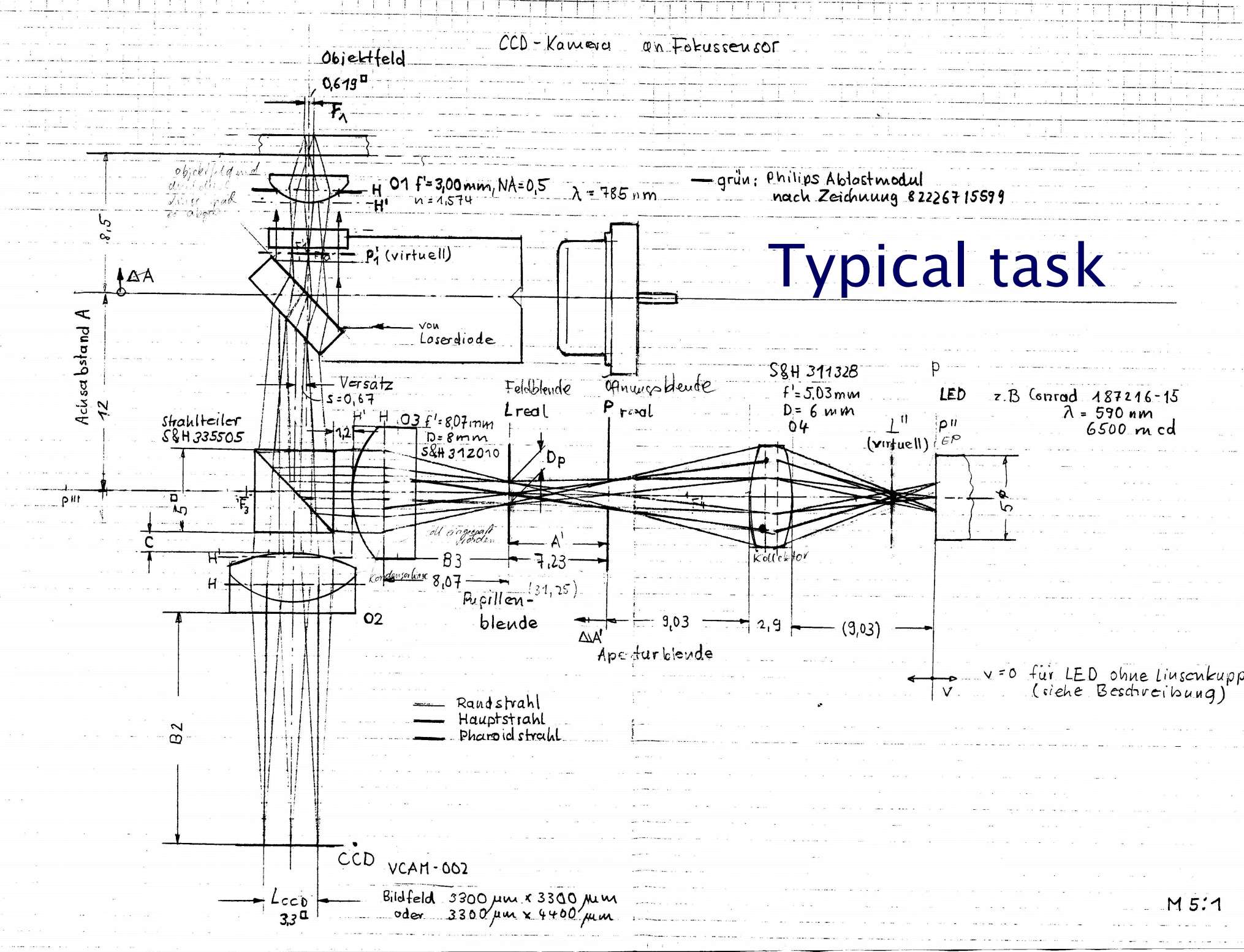


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Motivation

Illumination for a measuring microscope with focus sensor and CCD-camera



How can the optical layout be optimized?

Figure 1: Basic structure of the double imaging optical system example

Possible system parameters in PARAX

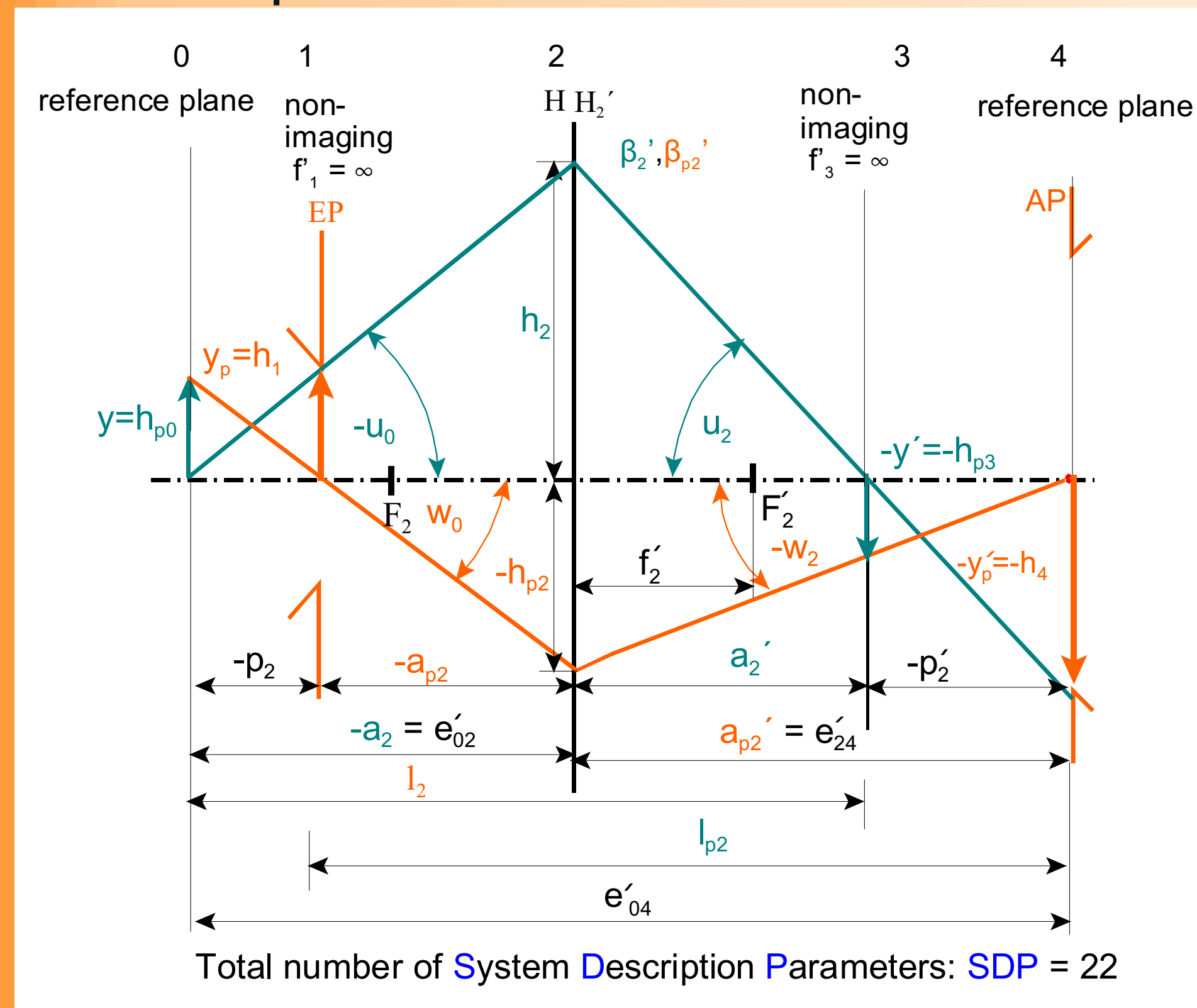


Figure 3: Possible local and global system parameters for a double imaging optical system with 5 planes

Degree of freedom and basic equations

Degrees of Freedom (FG):
= number of independent predefined system variables

$$FG(k) = 3 + 2(k - 1)$$

$$k = 5 \Rightarrow FG = 11$$

k - Number of planes (system components)

Number of basic arithmetic combinations:

$$C_{SDP}^{(FG)} = \binom{SDP}{FG}$$

For a double imaging optical system with 5 planes:

$$k = 5 \Rightarrow SDP = 22 \Rightarrow FG = 11$$

$$C_{SDP}^{(FG)} = \binom{SDP}{FG} = \binom{22}{11} = 705432$$

Linking the marginal ray and the chief ray via the Helmholtz-Lagrange-Invariant:

$$h'_{pi} \tan u'_i - h'_i \tan w'_i = h_{pi} \tan u_i - h_i \tan w_i$$

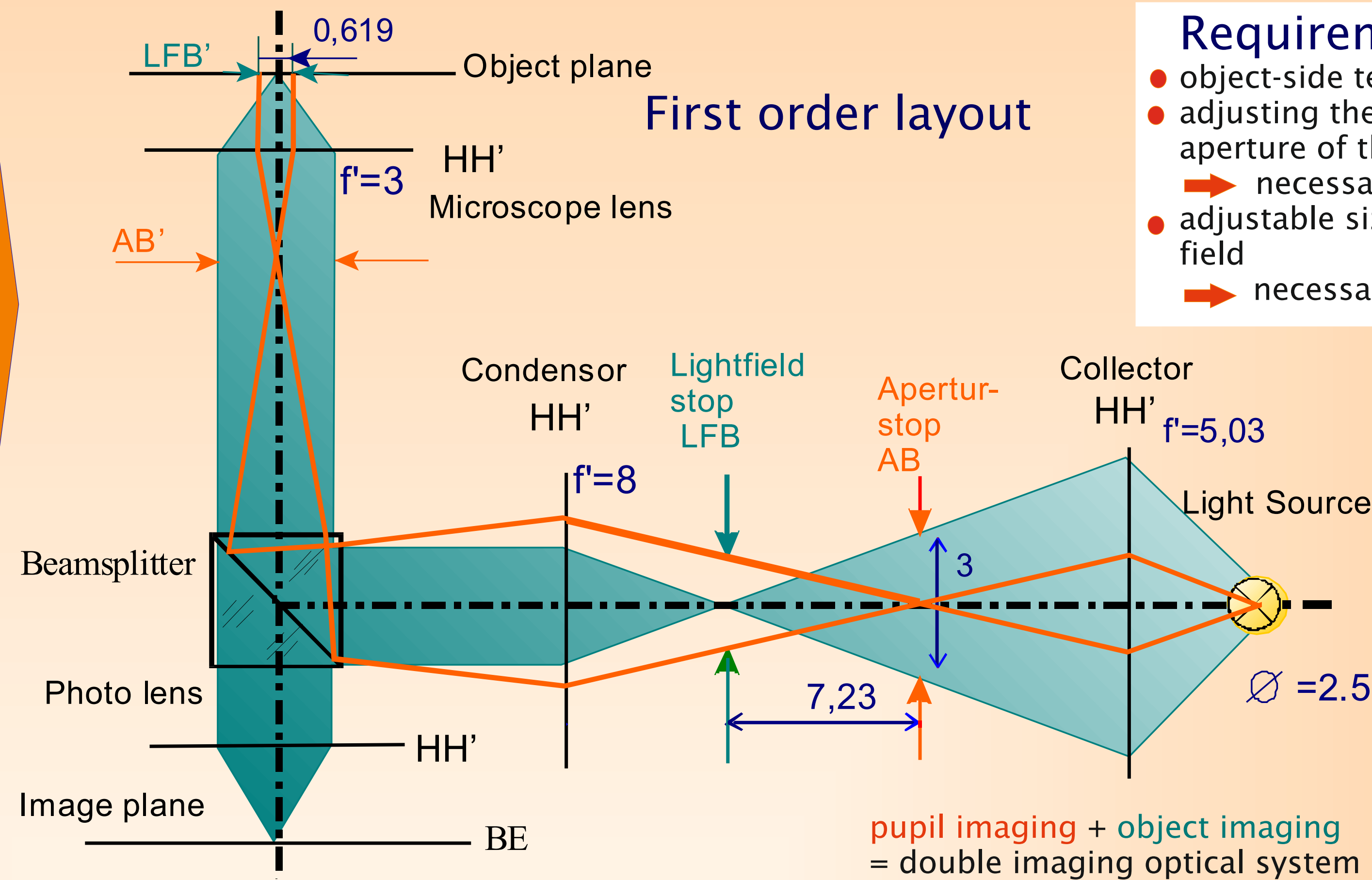
Helmholtz-Lagrange-Invariant for the pupil imaging:

$$\beta'_i \beta_{pi} = \frac{p'_i}{p_i} \Rightarrow \frac{y'_i y'_{pi}}{p'_i} = \frac{y_i y_{pi}}{p_i}$$

References

- [1] B. Mitschunas, B. Rudolf, R. Bielert, J. Mitschunas: Kollineare Modellierung komplexer optischer Systeme, Photonik 2.2016, S 46-49
- [2] W. Richter, B. Mitschunas: Paraxialer Entwurf optischer Systeme, F & M 100 (1992) 10, 459-463
- [3] T. Kryszczyński, M. Lesniewski: Method of the initial optical design and its realization, Proc. of SPIE Vol. 5954 595411-1, 2005

Example Adapting the illumination system to the imaging system

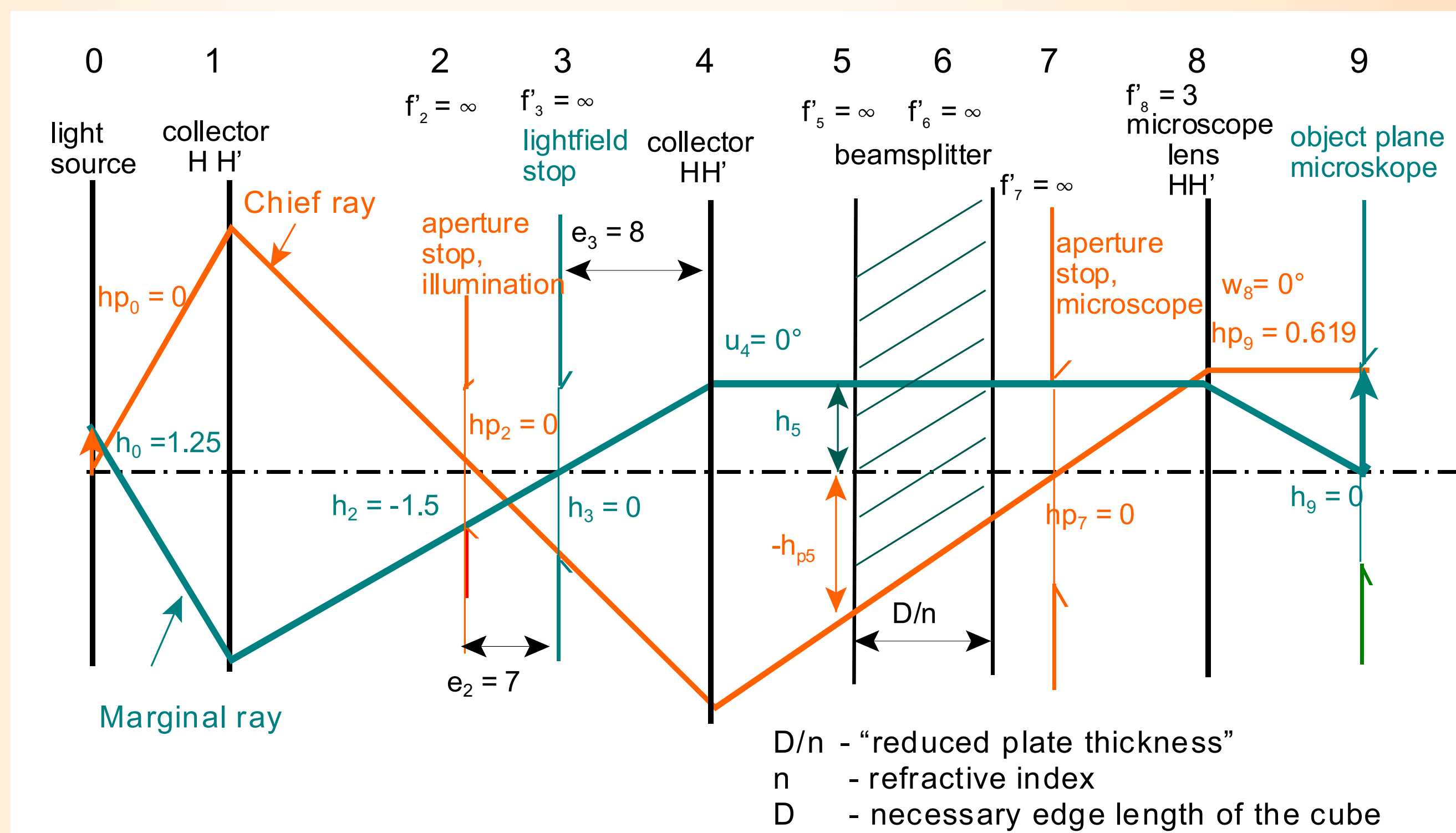


Requirements

- object-side telecentric beam path
- adjusting the aperture of the illumination to the aperture of the microscope
 - necessary variable aperture stop
- adjustable size of the illumination of the object field
 - necessary variable field stop

Figure 2: Basic principle of the optical system

Derivation of local and global system parameters for the input tables in PARAX



Global parameters:

- lateral magnification: $\beta'_{48} = -0.38$
- pupil imaging magnification: $\beta'_{p14} = 1.34$

Degree of freedom for the example:

$$k = 10 \Rightarrow FG = 21$$

Figure 4: 19 local and 2 global system default values for initial step optical design with Parax

Free radius of the optical element on plane „i“:

$$\rho_i = |h_{pi}| + |h_i|$$

Free aperture of the optical element on plane „i“:

$$K_i = \frac{2\rho_i}{f'_i}$$

Free radius on plane 5= necessary half edge length of the beam splitter cube

Results with analysis tools

Local variables	Plane0	Plane1	Plane2	Plane3	Plane4	Plane5	Plane6	Plane7	Plane8	Plane9
F: Effective focal length	5.020000000	0.000000000	0.000000000	0.000000000	0.000000000	0.000000000	0.000000000	0.000000000	0.000000000	0.000000000
x: Distance between one and the next plane	9.263531590	11.006310667	7.000000000	7.894739842	8.795757386	5.000000000	3.000000000	3.000000000	3.000000000	0.000000000
h: Marginal ray height	1.262484570	-3.458495143	-0.000000000	1.691729323	1.691729323	1.691729323	1.691729323	1.691729323	1.691729323	0.000000000
w: Half maximal aperture angle	28.93438657	-12.094757077	-12.094757077	0.000000000	0.000000000	0.000000000	0.000000000	0.000000000	29.419076152	0.000000000
l: Lateral magnification	-3.579763433	1.800000000	1.000000000	0.000000000	1.800000000	1.000000000	1.000000000	0.000000000	0.000000000	0.000000000
l: Imaging length	24.866986736	0.000000000	0.000000000	0.000000000	0.000000000	0.000000000	0.000000000	0.000000000	0.000000000	0.000000000
a: Object distance	-6.979770699	7.000000000	0.000000000	-7.894739842	0.000000000	0.000000000	0.000000000	0.000000000	0.000000000	0.000000000
a': Image distance	2.283755521	18.006310667	7.000000000	0.000000000	0.000000000	0.000000000	0.000000000	0.000000000	3.000000000	0.000000000
hp: Chief ray height	0.000000000	-2.561242971	0.000000000	1.628947386	3.466106055	1.650666667	0.619000000	0.000000000	-0.619000000	-0.619000000
w: Half maximal field angle	15.45412023	-13.099971593	-13.099971593	11.658420337	11.658420337	11.658420337	11.658420337	11.658420337	0.000000000	0.000000000
lpi: Lateral pupil magnification	-1.188133333	1.000000000	1.000000000	-1.178195449	1.000000000	1.000000000	1.000000000	0.000000000	0.000000000	0.000000000
lp: Pupil magnification	20.26842257	0.000000000	0.000000000	31.69312228	0.000000000	0.000000000	0.000000000	0.000000000	-3.000000000	0.000000000
ap: Entrance pupil distance	-6.263531590	0.000000000	-7.000000000	-14.894739842	0.000000000	0.000000000	0.000000000	0.000000000	0.000000000	0.000000000
ap': Exit pupil distance	11.006310667	0.000000000	0.000000000	16.789573386	0.000000000	0.000000000	0.000000000	0.000000000	0.000000000	0.000000000
p: Distance pupil-object/image	2.283755521	7.000000000	7.000000000	0.000000000	0.000000000	0.000000000	0.000000000	0.000000000	0.000000000	0.000000000
p': Free radial distance	1.262484570	6.419738114	1.500000000	1.628947386	5.157853378	3.342399999	2.30729323	2.30729323	0.619000000	0.000000000
K: Relative aperture	2.552579797	0.000000000	0.000000000	1.306651629	0.000000000	0.000000000	0.000000000	0.000000000	1.540486216	0.000000000

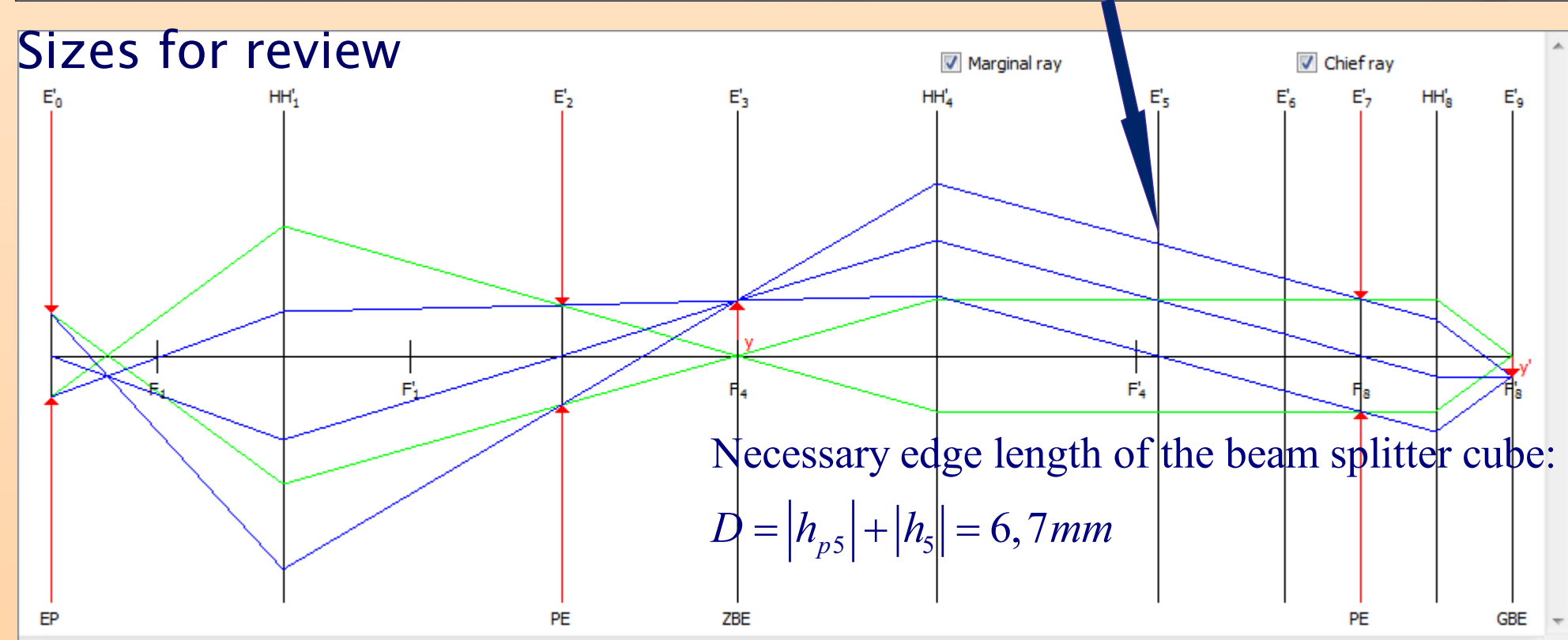


Figure 5: Input and results table (Input values in black)

Figure 6: Delano diagram - a powerful visual design tool

Figure 7: Parameter variation and parameter iteration

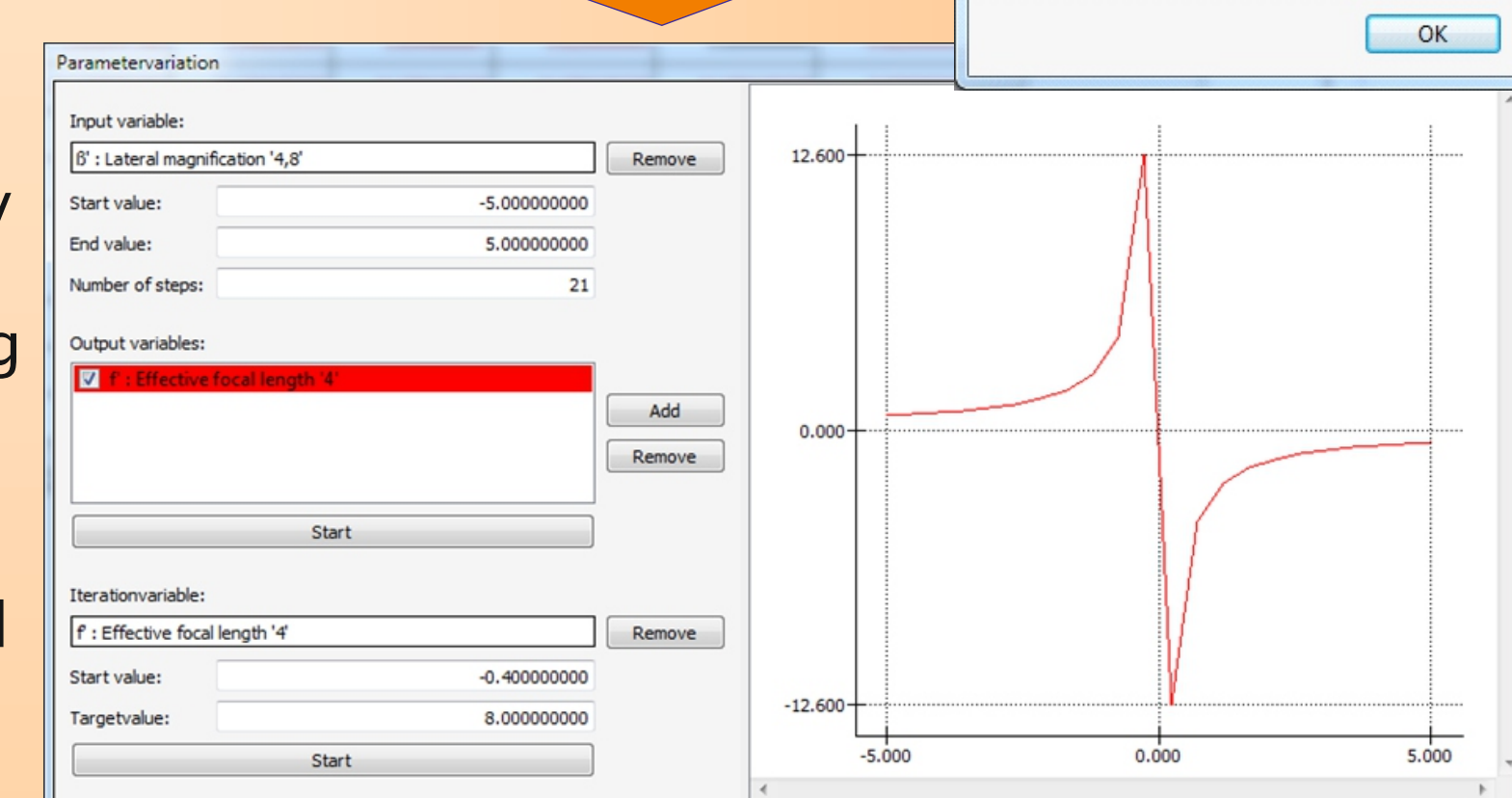


Figure 8: Ray tracing with both imaging paths:
1. for the on-axis point
2. for a field point

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